

# Telescope Calibration & Alignment or Wavefront Sensing



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## Profile



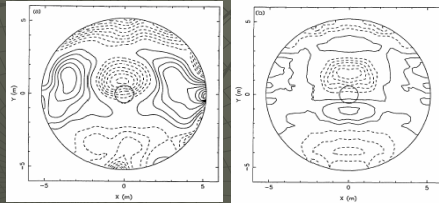
- ◆ **Gene Serabyn**
  - **JPL**
    - ◆ Senior Research Scientist 3/1998 –
    - ◆ Infrared interferometry, nulling, coronagraphy
  - **Caltech**
    - ◆ Visiting Associate 1/1987 –
    - ◆ Sub-millimeter wavefront sensing, spectroscopy, imaging

## Scope



### ◆ Submillimeter Wavefront Sensing System

- To optimize the telescope's main beam efficiency,
  - ◆ Need detailed knowledge of the telescope surface shape.
- Metrology can hold a given shape,
  - ◆ but need to know what the shape is.
- Mechanical models need to be calibrated.



- Goal: Measure the wavefront reflected by the telescope, somewhere in the telescope's observing passband
- Scope: Proof-of-concept design that meets the accuracy requirement

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## Scope



- ◆ Use of large-format submm arrays is assumed
  - Opens the door to "optical" techniques
- ◆ Wavefront quality (pupil plane) and image quality (focal plane) are Fourier conjugates
  - Not a vital trade at this point
- ◆ Proven CSO approach used as a sanity check
  - Previously, accuracy of 9  $\mu\text{m}$  achieved

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## Requirements for Subsystem



- ◆ **Wavefront map of the combined primary/secondary reflector surfaces**
  - Accuracy – small contributor to the error budget
    - ◆ a few (1-3)  $\mu\text{m}$
  - Lateral resolution
    - lo-res (gravitational flexure;  $\approx 1$  point per panel)
    - ◆  $16 \times 16$
    - goal (panel shapes)
    - ◆  $32 \times 32$  to  $48 \times 48$  pixels
  - Time resolution – small elevation angle range
    - ◆  $5-10^\circ$  (under an hour)
  - Measurement interval – access “every few months”
    - ◆ (translates to source availability; number and flux)
  - Measurement wavelength – use a facility “submm” camera
    - ◆ **0.3 to 3 mm**

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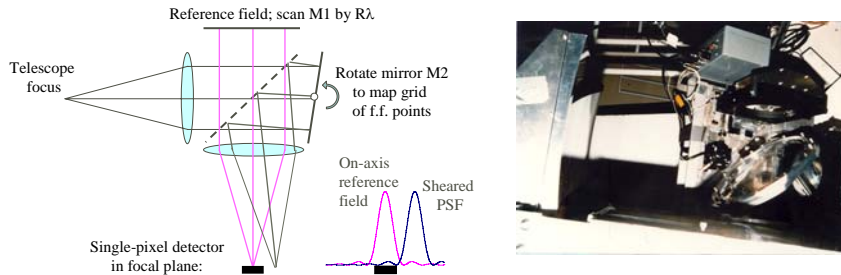
## Key Design Issues and Parameters



- ◆ Accuracy goal is a factor of 3 beyond current systems
- ◆ Small number of appropriate astronomical sources
- ◆ **Examine:**
  - Ultimate measurement accuracy
    - ◆ Dependence on source flux and thermal background noise
  - Optimal measurement wavelength

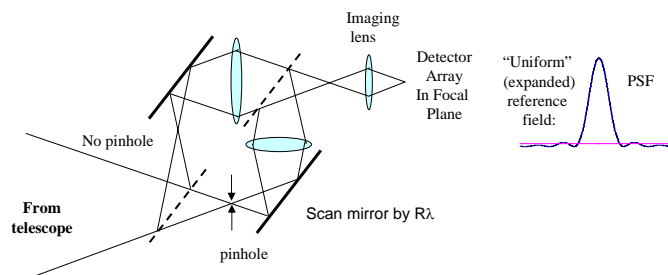
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## System Design: Option 1



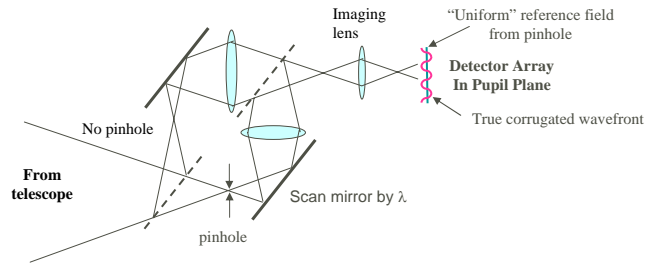
- Shearing interferometer: focal plane sensing with single pixel detector
- Proven at CSO:
  - 9  $\mu\text{m}$  accuracy
  - 15 $\times$ 15 and 21 $\times$ 21 maps made
  - few hour measurement timescale achieved
- Can be improved significantly in terms of efficiency
- Point-by-point approach will always introduce systematic errors

## System Design: Option 2



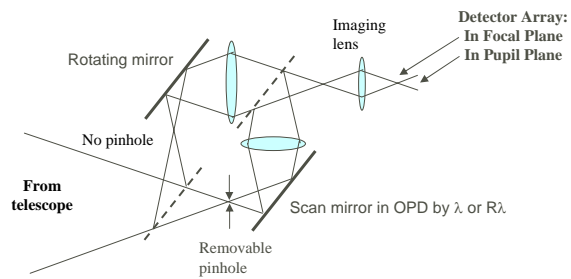
- Focal-plane Point Diffraction Interferometer
- Spreads out the energy of the reference beam
- Makes use of array detectors to instantaneously sense full focal plane field
- Lower instantaneous SNR per point
- Gains in the areas of stability and systematics

## System Design: Option 3



- Pupil-plane Point Diffraction Interferometer
- Switch to pupil-plane sensing in this approach, as in the optical
- Only need to scan one mirror by  $1-\lambda$

## System Design: Hybrid Option



Hybrid Interferometer: focal-plane and/or pupil-plane sensing

## Supporting Analysis I



- ◆ **FOV large:**
  - $32F\lambda \approx 300 \lambda \approx 0.1 - 1.0 \text{ m}$
- ◆ **Mirrors large:**
  - Of order 1-2 m if long wavelengths are included

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## Supporting Analysis II



- ◆ **Ultimate sensitivity of submm wavefront sensors depends on:**
  - Phase measurement accuracy in the presence of long- $\lambda$  background noise
- ◆ **Start with pupil plane measurement case:**
  - Phase accuracy:  $\phi = 1/\text{SNR} = \text{sqrt}(N_{\text{background}})/N_{\text{signal}}$
  - **Signal:**
    - ◆ Source flux per subaperture
      - (only Mars, Uranus, Neptune are small and bright enough)
    - ◆ Atmospheric and instrumental transmission (T)
  - **Noise:**
    - ◆ Number of background modes transmitted by cold stop
    - ◆ Bose-Einstein statistics:  $\Delta n = \text{sqrt}(n(n+1))$

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## Supporting Analysis III



### ◆ End with:

- $\Delta x \approx \lambda / (100T\sqrt{t})$
- Approximately proportional to  $\lambda$ 
  - ◆ (Both signal and noise vary with  $\lambda$  differently)
  - ◆ Short wavelengths have higher accuracy (assuming reasonable atmospheric transmission)
- Calculate time to reach 3- $\sigma$  sensitivity of 3  $\mu\text{m}$  (in a sq. m).
  - ◆ Assume  $T_{\text{inst}} \approx 0.1$  (largely the pinhole)
  - ◆ Assume  $T_{\text{atm}}(350) = 0.7$ ;  $T_{\text{atm}}(1300) = 0.97$

$\lambda$ ( $\mu\text{m}$ )	Time (sec)
350	25
1300	240

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## Critical Risk Assessment



- ◆ Fifteen years ago, the CSO shearing interferometry approach reached an accuracy of 9  $\mu\text{m}$  with a less than optimized system.
- ◆ To reach better sensitivities, the choice is:
  - Improve a known technique, or try a new approach
- ◆ The hybrid system described allows both
- ◆ The new approaches can be tried at existing telescopes before CCAT (if funding is available)
- ◆ Theoretical sensitivity limits are quite good.
  - Feel confident that a factor of 3 can be gained.
- ◆ **The main fundamental problem is thus the limited number of sources which are bright enough and small enough ( $< \lambda/D$ ).**
- ◆ Next phase concerns are then instrument-definition related: detailed throughput, sensitivity and aberration analyses, a diffraction analysis of the pupil plane approach,